

# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

August 21, 2009

Basics about the  
camera

#### Camera Descriptions

- Effective resolution: Up to 4096 pixels/line @ up to 39k line per second.
- Camera Link MEDIUM interface (2 to 4 taps, and 8, 10 or 12-bit).
- External and internal sync.
- External or internal exposure control.
- 40 or 80 MHz pixel clock rate.

#### Interface Mode

- Fixed line scan rate<sup>1</sup>
- Variable line scan rate<sup>2</sup>
- Variable line scan rate using the Rotary Encoder<sup>2</sup>
- Fixed line scan rate with frame trigger<sup>1</sup>
- Variable line scan rate with frame trigger<sup>2</sup>
- Variable line scan rate using the Rotary Encoder with frame trigger<sup>2</sup>
- Fixed line scan rate with variable frame size<sup>1</sup>
- Variable line scan rate with variable frame size<sup>2</sup>
- Variable line scan rate using the Rotary Encoder with frame trigger<sup>2</sup>

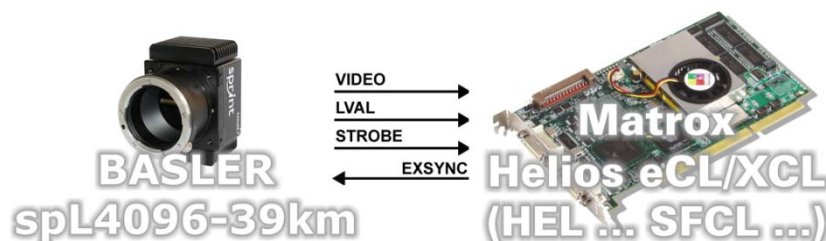
Mode of operations as  
per Matrox Imaging (in  
parentheses as per  
camera manufacturer)

Basics about the  
interface modes

#### Camera Interface Briefs

##### Mode 1: Fixed line scan rate

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL sending periodic EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsFLS.DCF](#)



<sup>1</sup> EXSYNC, level-controlled or Free Run programmable

<sup>2</sup> EXSYNC, level-controlled

# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

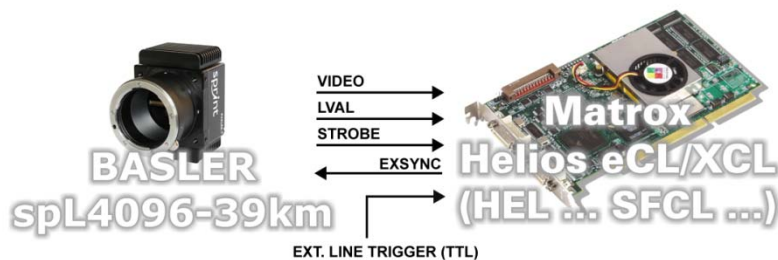
August 21, 2009

Basics about the  
interface modes

#### Camera Interface Briefs

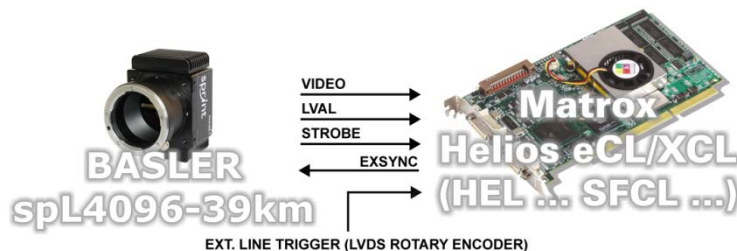
##### *Mode 2: Variable line scan rate*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external TTL line trigger signal.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLS.DCF](#)



##### *Mode 3: Variable line scan rate with rotary encoder*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external LVDS line trigger (ROTARY ENCODER) signal.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLSRE.DCF](#)



# Matrox Helios eCL/XCL

## Camera Interface Application Note

**BASLER spL4096-39km**

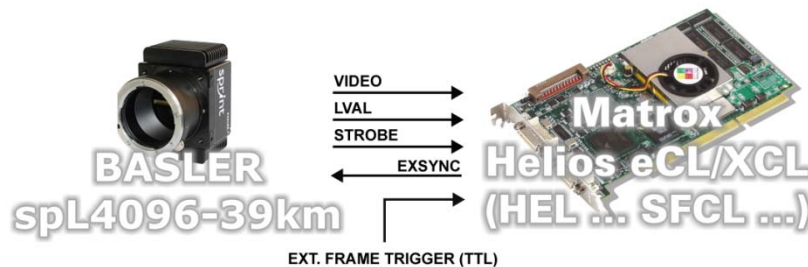
**August 21, 2009**

*Basics about the  
interface modes*

### Camera Interface Briefs (cont.)

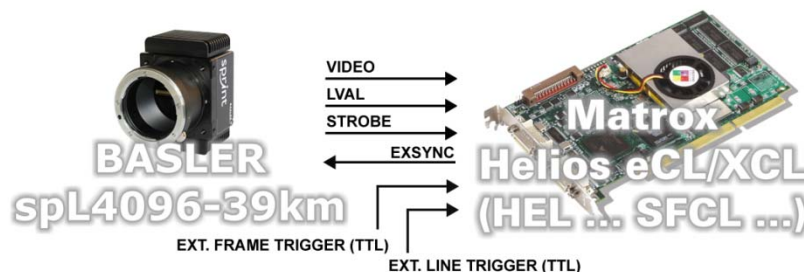
#### **Mode 4: Fixed line scan rate with frame trigger**

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external TTL frame (virtual) trigger signal.
- Matrox Helios eCL/XCL eCL/XCL sending periodic EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsFLSFT.DCF](#)



#### **Mode 5: Variable line scan rate with frame trigger**

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external TTL frame (virtual) and line trigger signals.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLSFT.DCF](#)



# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

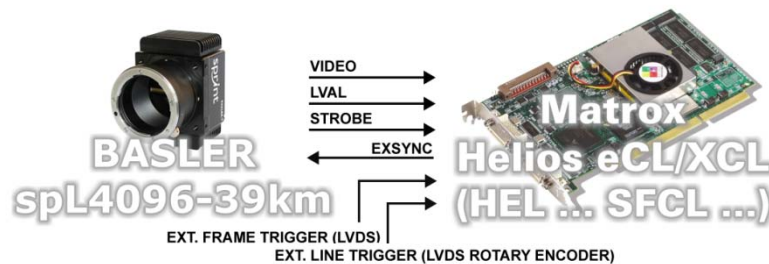
August 21, 2009

Basics about the  
interface modes

#### Camera Interface Briefs (cont.)

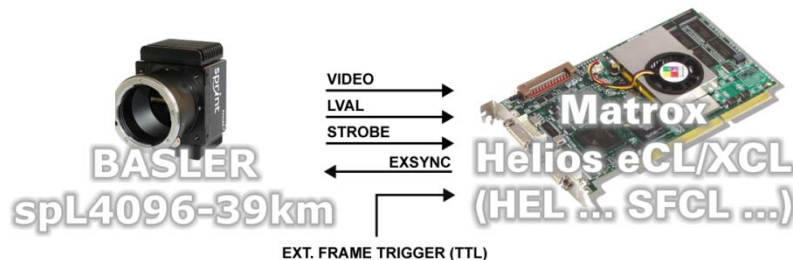
##### *Mode 6: Variable line scan rate with rotary encoder and frame trigger*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external LVDS frame (virtual) and external LVDS line trigger (ROTARY ENCODER) signals.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLSREFT.DCF](#)



##### *Mode 7: Fixed line scan rate with variable frame size*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external TTL frame (virtual) trigger signal.
- Matrox Helios eCL/XCL eCL/XCL sending periodic EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsFLSVF.DCF](#)



# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

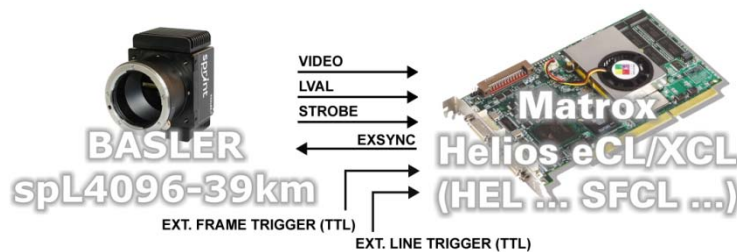
August 21, 2009

Basics about the  
interface modes

#### Camera Interface Briefs (cont.)

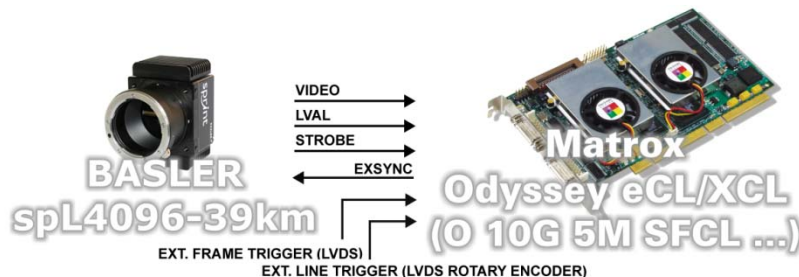
##### *Mode 8: Variable line scan rate with variable frame size*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external TTL frame (virtual) and line trigger signals.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLSVF.DCF](#)



##### *Mode 9: Variable line scan rate with rotary encoder and variable frame size*

- 4096 pixels/line.
- Camera Link MEDIUM interface (four 12-bit taps).
- DCF configured for 1000 lines per virtual frame.
- Matrox Helios eCL/XCL eCL/XCL receiving external LVDS frame (virtual) and external LVDS line trigger (ROTARY ENCODER) signals.
- Matrox Helios eCL/XCL eCL/XCL sending EXPOSURE1 (EXSYNC) signal to camera.
- Matrox Helios eCL/XCL eCL/XCL receiving LVAL, PIXEL CLOCK (@ 80 MHz) and video data from camera.
- DCF used: [SpL4096\\_39km\\_4096\\_12bit4tapsVLSREVF.DCF](#)



# Matrox Helios eCL/XCL

## Camera Interface Application Note

BASLER spL4096-39km

August 21, 2009

Specifics about the  
interface modes

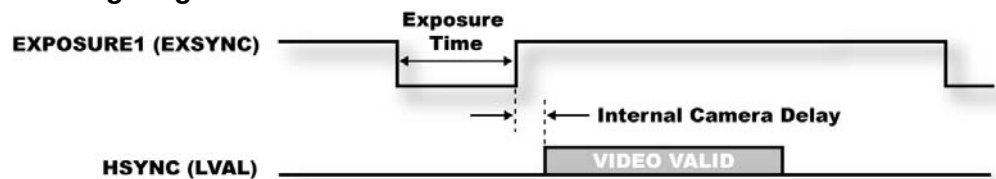
### Camera Interface Details

#### Mode 1: Fixed line scan rate

- **Line rate:** The frequency of the periodic EXPOSURE1 (EXSYNC) signal determines the camera's line rate. The maximum line rate for this camera equals **39 kHz**.
- **Exposure time:** For **EXSYNC, level-controlled** mode the exposure time is the inactive (low level) period between the falling and rising edges of the EXPOSURE1 (EXSYNC) signal. The default exposure time for this DCF is **25  $\mu$ s**. Maximum/minimum exposure time per line for this DCF is **209 ms** and **12.5 ns** respectively. The exposure time can be modified in the DCF using Matrox Intellicam or with the MIL MdigControl() function. Consult the respective manual for more information.
- **Camera communication:** This DCF will work with all **Free Run** and **EXSYNC** modes however **EXSYNC, Level controlled** is the recommended mode for use with this DCF. Set the mode using the Basler Camera Configuration Tool Plus (CCT+). Refer to the camera manual for additional information.

| Parameter                  | Setting                  |
|----------------------------|--------------------------|
| Video Data Output Mode     | 4 taps, 12-bits          |
| Exposure Time Control Mode | EXSYNC, Level-controlled |

#### ▪ Timing diagram:



#### Mode 2: Variable line scan rate

- **Line rate:** The line rate is controlled by the frequency of the external TTL line trigger signal. The line trigger signal period must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.5 \mu$ s) or slower than the maximum line rate of the camera.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.



# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

August 21, 2009

Specifics about the  
interface modes

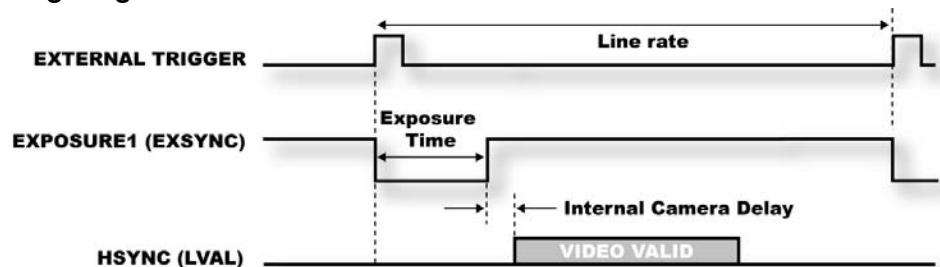
#### Camera Interface Details (cont.)

##### Mode 2: Variable line scan rate

- **Camera communication:** This DCF works with all **EXSYNC** modes however **EXSYNC, Level-controlled** is the recommended mode for use with this DCF. Set the mode using the Basler Camera Configuration Tool Plus (CCT+). Refer to the camera manual for additional information.

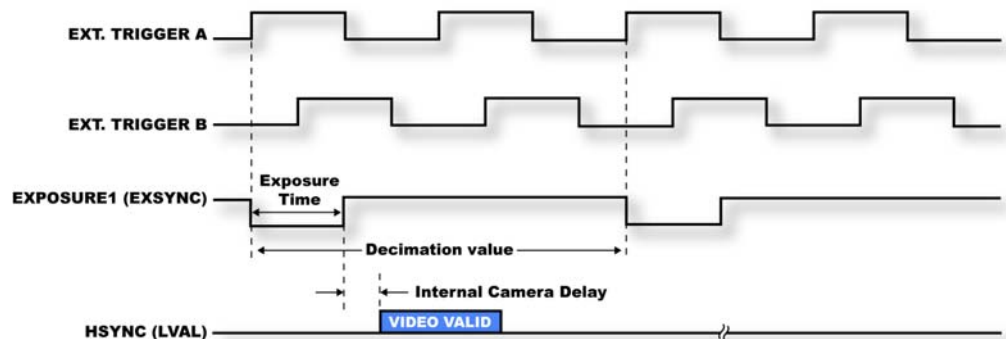
| Parameter                  | Setting                  |
|----------------------------|--------------------------|
| Video Data Output Mode     | 4 taps, 12-bits          |
| Exposure Time Control Mode | EXSYNC, Level-controlled |

- **Timing diagram:**



##### Mode 3: Variable line scan rate with rotary encoder

- **Line/frame rate:** The line rate is controlled by the frequency of the external LVDS line trigger signal with a Rotary Encoder format. With the Rotary Encoder approach, it is possible to force a certain decimation value to grab a line every x number of pulses from the line trigger (combination of the A and B signals). The line trigger signal controlled by the decimation value must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.50 \mu\text{s}$ ) or slower than the maximum line rate of the camera. The DCF is done for a forward direction from the Rotary Encoder.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 2: Variable line scan rate.
- **Timing diagram:**



\* The decimation value showed in this timing diagram is eight (8).

# Matrox Helios eCL/XCL

## Camera Interface Application Note

BASLER spL4096-39km

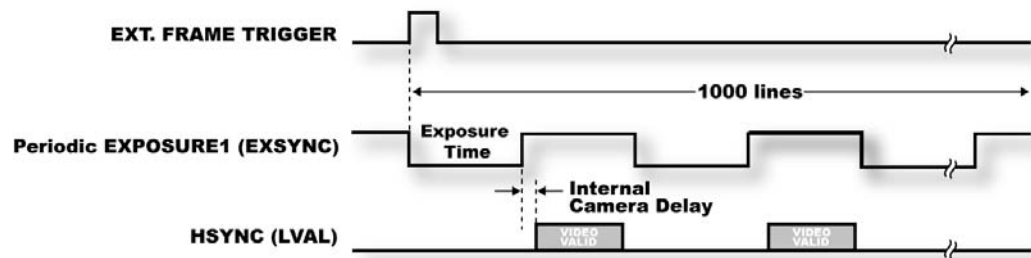
August 21, 2009

Specifics about the  
interface modes

### Camera Interface Details (cont.)

#### Mode 4: Fixed line scan rate with frame trigger

- **Line/frame rate:** The line rate is fixed and controlled by the frequency of EXPOSURE1 (EXSYNC) signal. The default exposure time for this DCF is **25  $\mu$ s**. The virtual frame rate is variable and controlled by the period of the external frame trigger signal, however the external frame trigger period must always be greater than the total time of the number of lines captured. The number of lines per virtual frame (maximum of 1000 for this DCF) is fixed and controlled by the vertical timing of the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 1: Fixed line scan rate.
- **Timing diagram:**



#### Mode 5: Variable line scan rate with frame trigger

- **Line/frame rate:** The line rate is controlled by the frequency of the external TTL line trigger signal. The line trigger signal period must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.50 \mu$ s) or slower than the maximum line rate of the camera. The default exposure time for this DCF is **25  $\mu$ s**. The virtual frame rate is variable and controlled by the period of the external frame trigger signal, however the external trigger period must always be greater than the total time of the number of lines captured. The number of lines per virtual frame (1000 for this DCF) is fixed and controlled by the vertical timing of the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 2: Variable line scan rate.

Continued....



# Matrox Helios eCL/XCL

## Camera Interface Application Note

BASLER spL4096-39km

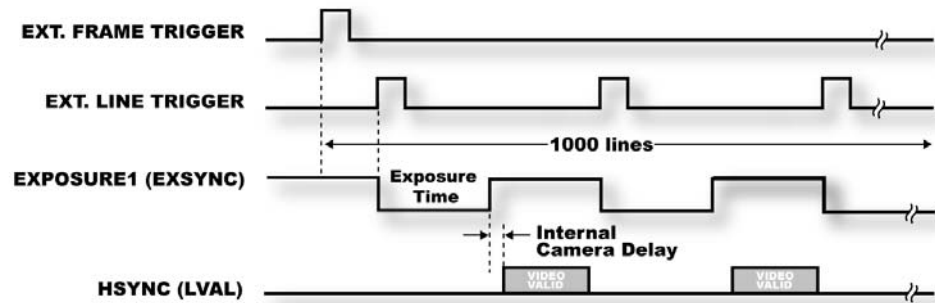
August 21, 2009

Specifics about the  
interface modes

### Camera Interface Details (cont.)

#### Mode 5: Variable line scan rate with frame trigger

- Timing diagram:



#### Mode 6: Variable line scan rate with rotary encoder and frame trigger

- **Line/frame rate:** The line rate is controlled by the frequency of the external LVDS line trigger signal with a Rotary Encoder format. With the Rotary Encoder approach, it is possible to force a certain decimation value to grab a line every x number of pulses from the line trigger (combination of the A and B signals). The line trigger signal controlled by the decimation value must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.50 \mu\text{s}$ ) or slower than the maximum line rate of the camera. The DCF is done for a forward direction from the Rotary Encoder. The number of lines per virtual frame (maximum of 1000 for this DCF) is variable and controlled by the frame trigger signal. Matrox Helios eCL/XCL eCL/XCL captures lines during the high level of the frame trigger signal. To modify the maximum amount of lines captured, change the active vertical timing period in the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 1: Fixed line scan rate.

# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

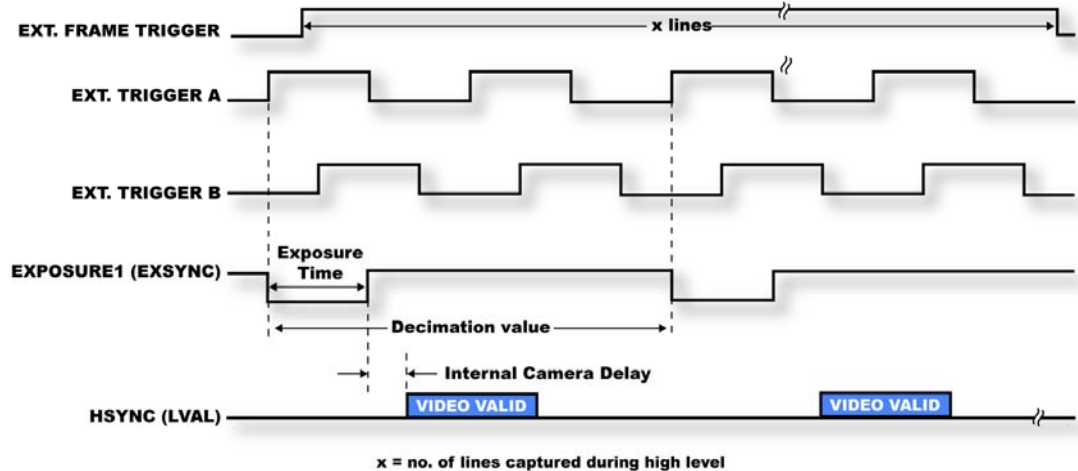
August 21, 2009

Specifics about the  
interface modes

#### Camera Interface Details (cont.)

##### Mode 6: Variable line scan rate with rotary encoder and frame trigger

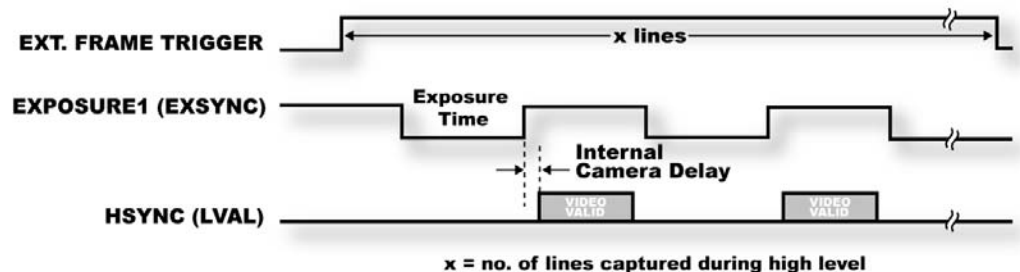
###### ▪ Timing diagram:



\* The decimation value shown in this timing diagram is eight (8).

##### Mode 7: Fixed line scan rate with variable frame size

- **Line/frame rate:** The line rate is fixed and controlled by the frequency of EXPOSURE1 (EXSYNC) signal. The default exposure time for this DCF is 25  $\mu$ s. The number of lines per virtual frame (maximum of 1000 for this DCF) is variable and controlled by the frame trigger signal. Matrox Helios eCL/XCL captures lines during the high level of the frame trigger signal. To modify the maximum amount of lines captured, change the active vertical timing period in the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 1: Fixed line scan rate.
- **Timing diagram:**



# Matrox Helios eCL/XCL

## Camera Interface Application Note

BASLER spL4096-39km

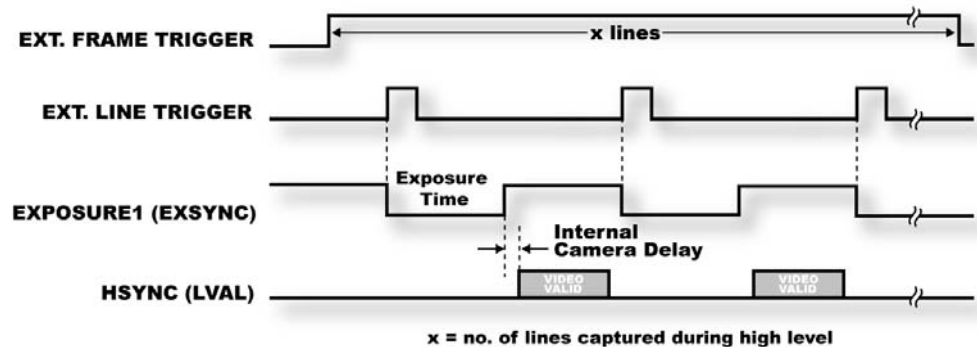
August 21, 2009

Specifics about the  
interface modes

### Camera Interface Details (cont.)

#### Mode 8: Variable line scan rate with variable frame size

- **Line/frame rate:** The line rate is variable and controlled by the external line trigger frequency. The line trigger signal period must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.50 \mu\text{s}$ ) or slower than the maximum line rate of the camera. The default exposure time for this DCF is **25  $\mu\text{s}$** . The number of lines per virtual frame (maximum of 1000 for this DCF) is variable and controlled by the frame trigger signal. Matrox Helios eCL/XCL eCL/XCL captures lines during the high level of the frame trigger signal. To modify the maximum amount of lines captured, change the active vertical timing period in the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.
- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 2: Variable line scan rate.
- **Timing diagram:**



#### Mode 9: Variable line scan rate with rotary encoder and variable frame size

- **Line/frame rate:** The line rate is controlled by the frequency of the external LVDS line trigger signal with a Rotary Encoder format. With the Rotary Encoder approach, it is possible to force a certain decimation value to grab a line every x number of pulses from the line trigger (combination of the A and B signals). The line trigger signal controlled by the decimation value must be larger than the total duration of the exposure time (low level duration of the timer), the internal delay of the camera ( $\approx 2.50 \mu\text{s}$ ) or slower than the maximum line rate of the camera. The DCF is done for a forward direction from the Rotary Encoder. The number of lines per virtual frame (maximum of 1000 for this DCF) is variable and controlled by the frame trigger signal. Matrox Helios eCL/XCL eCL/XCL captures lines during the high level of the frame trigger signal. To modify the maximum amount of lines captured, change the active vertical timing period in the DCF. Capture of the lines will start with the rising edge of the frame trigger signal.

Continued...

# Matrox Helios eCL/XCL

## Camera Interface Application Note

**BASLER spL4096-39km**

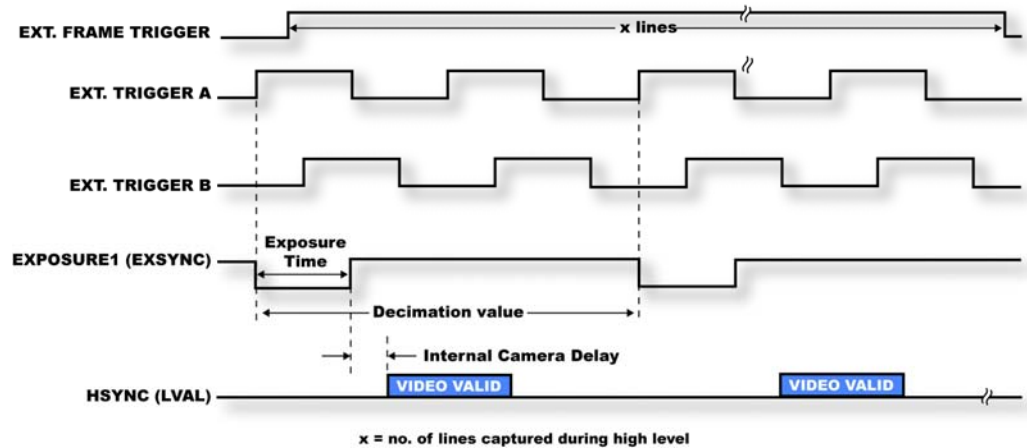
**August 21, 2009**

Specifics about the  
interface modes

### Camera Interface Details (cont.)

#### *Mode 9: Variable line scan rate with rotary encoder and variable frame size*

- **Exposure time:** Refer to Mode 1: Fixed line scan rate.
- **Camera communication:** Refer to Mode 2: Variable line scan rate.
- **Timing diagram:**



\* The decimation value showed in this timing diagram is eight (8).

Cabling details for the  
interface modes

### Cabling Requirements

#### *Mode 1: Fixed line scan rate*

- **Cable and Connection:** Standard Camera Link cable.

#### *Mode 2: Variable line scan rate*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External line trigger should be connected to the 9-pin connector on the External I/O adapter bracket:

#### EXTERNAL I/O BRACKET

(9-pin connector)

| Pin Name       | Pin no. | External Trigger Source     |
|----------------|---------|-----------------------------|
| OPTO_AUX_IN0 + | 07      | ← LINE TRIGGER (TTL FORMAT) |
| OPTO_AUX_IN0 - | 02      | ← LINE TRIGGER (GROUND)     |

# Matrox Helios eCL/XCL

## Camera Interface Application Note

BASLER spL4096-39km

August 21, 2009

Cabling details for the  
interface modes

### Cabling Requirements

#### *Mode 3: Variable line scan rate with rotary encoder*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External line trigger should be connected to the 9-pin and 44-pin connectors on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin Name          | Pin no. |   | External Trigger Source<br>Pin Name |
|-------------------|---------|---|-------------------------------------|
| P0_LVDS_AUX_IN0 + | 08      | ← | Line TRIGGER A + (LVDS FORMAT)      |
| P0_LVDS_AUX_IN0 - | 03      | ← | Line TRIGGER A - (LVDS FORMAT)      |

###### (44-pin connector)

| Pin Name          | Pin no. |   | External Trigger Source<br>Pin Name |
|-------------------|---------|---|-------------------------------------|
| P0_LVDS_AUX_IN1 + | 37      | ← | Line TRIGGER B + (LVDS FORMAT)      |
| P0_LVDS_AUX_IN1 - | 23      | ← | Line TRIGGER B - (LVDS FORMAT)      |

#### *Mode 4: Fixed line scan rate with frame trigger*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame trigger should be connected to the 9-pin connector on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin Name       | Pin no. |   | External Trigger Source<br>Pin Name |
|----------------|---------|---|-------------------------------------|
| OPTO_AUX_IN1 + | 04      | ← | FRAME TRIGGER (TTL FORMAT)          |
| OPTO_AUX_IN1 - | 05      | ← | FRAME TRIGGER (GROUND)              |

#### *Mode 5: Variable line scan rate with frame trigger*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame/line triggers should be connected to the 9-pin connector on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin name       | Pin no. |   | External Trigger Sources<br>Pin name |
|----------------|---------|---|--------------------------------------|
| OPTO_AUX_IN1 + | 04      | ← | FRAME TRIGGER (TTL FORMAT)           |
| OPTO_AUX_IN1 - | 05      | ← | FRAME TRIGGER (GROUND)               |
| OPTO_AUX_IN0 + | 07      | ← | LINE TRIGGER (TTL FORMAT)            |
| OPTO_AUX_IN0 - | 02      | ← | LINE TRIGGER (GROUND)                |

# Matrox Helios eCL/XCL

## Camera Interface Application Note

**BASLER spL4096-39km**

**August 21, 2009**

*Cabling details for the  
interface modes*

### Cabling Requirements

#### *Mode 6: Variable line scan rate with rotary encoder and frame trigger*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame/line triggers should be connected to the 9-pin and 44-pin connectors on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin name          | Pin no. |   | External Trigger Sources<br>Pin name |
|-------------------|---------|---|--------------------------------------|
| P0_LVDS_AUX_IN0 + | 08      | ← | Line TRIGGER A + (LVDS FORMAT)       |
| P0_LVDS_AUX_IN0 - | 03      | ← | Line TRIGGER A - (LVDS FORMAT)       |

###### (44-pin connector)

| Pin name          | Pin no. |   | External Trigger Sources<br>Pin name |
|-------------------|---------|---|--------------------------------------|
| P0_LVDS_AUX_IN1 + | 37      | ← | Line TRIGGER B + (LVDS FORMAT)       |
| P0_LVDS_AUX_IN1 - | 23      | ← | Line TRIGGER B - (LVDS FORMAT)       |
| LVDS_AUX_IN1 +    | 12      | ← | FRAME TRIGGER (LVDS FORMAT)          |
| LVDS_AUX_IN1 -    | 28      | ← | FRAME TRIGGER (LVDS FORMAT)          |

#### *Mode 7: Fixed line scan rate with variable frame size*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame trigger should be connected to the 9-pin connector on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin name       | Pin no. |   | External Trigger Sources<br>Pin name |
|----------------|---------|---|--------------------------------------|
| OPTO_AUX_IN1 + | 04      | ← | FRAME TRIGGER (TTL FORMAT)           |
| OPTO_AUX_IN1 - | 05      | ← | FRAME TRIGGER (GROUND)               |

#### *Mode 8: Variable line scan rate with variable frame size*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame/line triggers should be connected to the 9-pin connector on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET

###### (9-pin connector)

| Pin name       | Pin no. |   | External Trigger Sources<br>Pin name |
|----------------|---------|---|--------------------------------------|
| OPTO_AUX_IN1 + | 04      | ← | FRAME TRIGGER (TTL FORMAT)           |
| OPTO_AUX_IN1 - | 05      | ← | FRAME TRIGGER (GROUND)               |
| OPTO_AUX_IN0 + | 07      | ← | LINE TRIGGER (TTL FORMAT)            |
| OPTO_AUX_IN0 - | 02      | ← | LINE TRIGGER (GROUND)                |



# Matrox Helios eCL/XCL

## Camera Interface Application Note

### BASLER spL4096-39km

August 21, 2009

Cabling details for the  
interface modes

#### Cabling Requirements

##### *Mode 9: Variable line scan rate with rotary encoder and variable frame size*

- **Cable and Connection:** Standard Camera Link.
- **External trigger:** External frame/line triggers should be connected to the 9-pin connector on the External I/O adapter bracket:

##### EXTERNAL I/O BRACKET (9-pin connector)

| Pin name          | Pin no. |   | External Trigger Sources<br>Pin name |
|-------------------|---------|---|--------------------------------------|
| P0_LVDS_AUX_IN0 + | 08      | ← | Line TRIGGER A + (LVDS FORMAT)       |
| P0_LVDS_AUX_IN0 - | 03      | ← | Line TRIGGER A - (LVDS FORMAT)       |

##### (44-pin connector)

| Pin name          | Pin no. |   | External Trigger Sources<br>Pin name |
|-------------------|---------|---|--------------------------------------|
| P0_LVDS_AUX_IN1 + | 37      | ← | Line TRIGGER B + (LVDS FORMAT)       |
| P0_LVDS_AUX_IN1 - | 23      | ← | Line TRIGGER B - (LVDS FORMAT)       |
| LVDS_AUX_IN1 +    | 12      | ← | FRAME TRIGGER (LVDS FORMAT)          |
| LVDS_AUX_IN1 -    | 28      | ← | FRAME TRIGGER (LVDS FORMAT)          |

The DCFs mentioned in this application note are also attached (embedded) to this PDF file – use the Adobe Reader's View File Attachment to access the DCF files. The information furnished by Matrox Electronics System, Ltd. is believed to be accurate and reliable. Please verify all interface connections with camera documentation or manual. Contact your local sales representative or Matrox Sales office or Matrox Imaging Applications at 514-822-6061 for assistance. © Matrox Electronic Systems Ltd, 2009-2011.

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